

Simulations of fracture process in concrete using a 3D lattice model

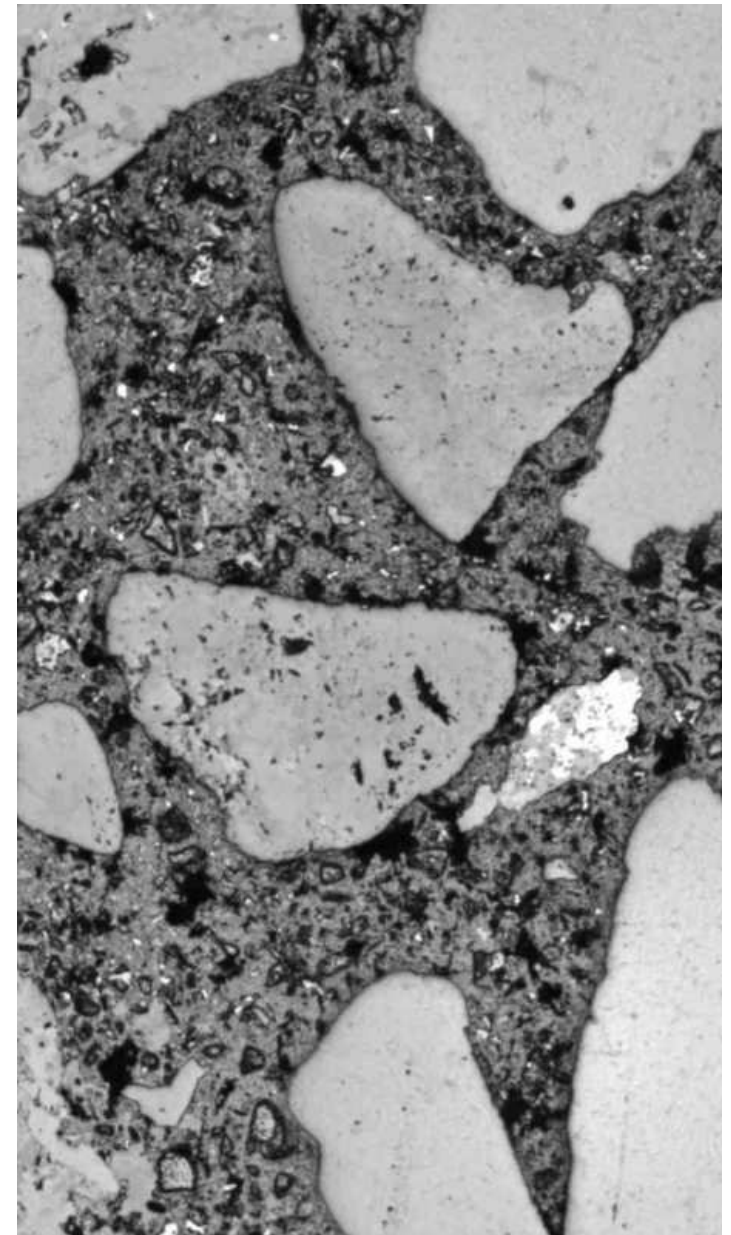
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- Engineering materials such as sand, concrete, rock, ceramics and polymers have common properties:
 - heterogeneity
 - anisotropy
 - discrete structure
 - nonlinear behaviour
- Two kinds of numerical models are commonly used:
 - **continuum models** (within fracture, damage, softening plasticity mechanics),
 - **discrete models** (molecular dynamics, discrete element method, lattice models).



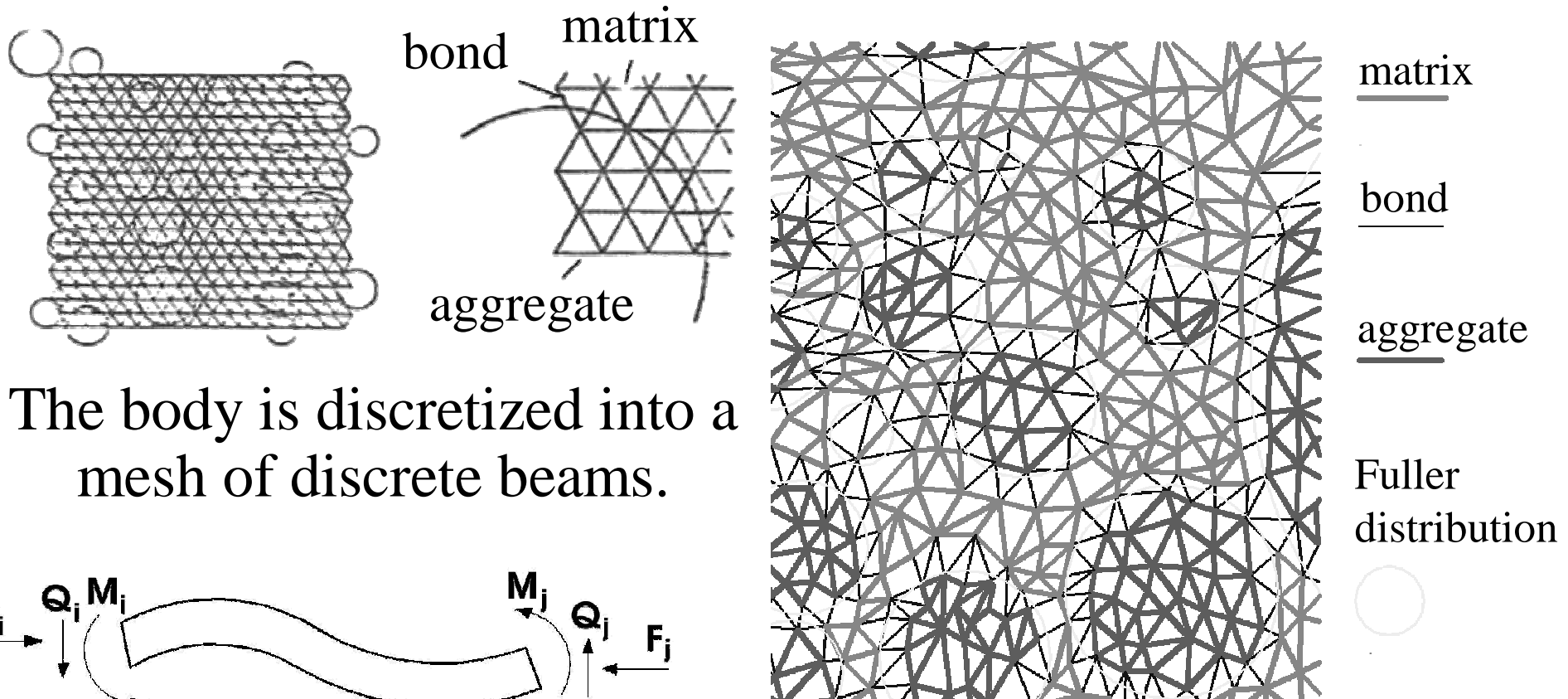
Structure of concrete

Aim

- The goal is to create a three dimensional discrete lattice model to describe the behavior of quasi-brittle materials.
- Investigate the effect of aggregates and interfacial zones on the 3D fracture process.
- Investigate the size effect on 3D specimens subject to uniaxial tension

To describe the fracture process in concrete on the scale of cement matrix and aggregates (meso scale) a lattice model was applied.

Original lattice model (Vervuut et al. 1994)



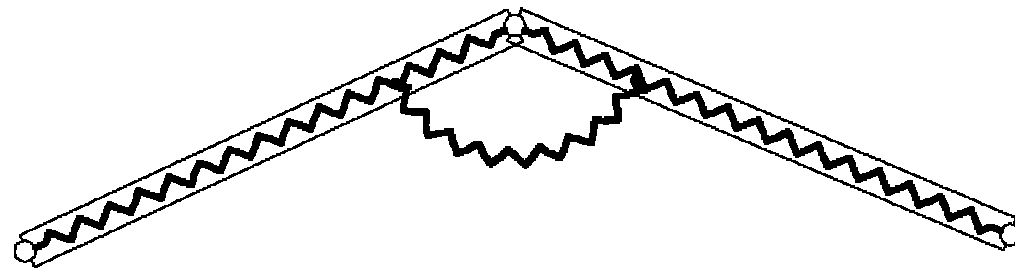
The body is discretized into a mesh of discrete beams.



Implicit FEM method is used

Different stiffness and strengths are assigned to various phases.

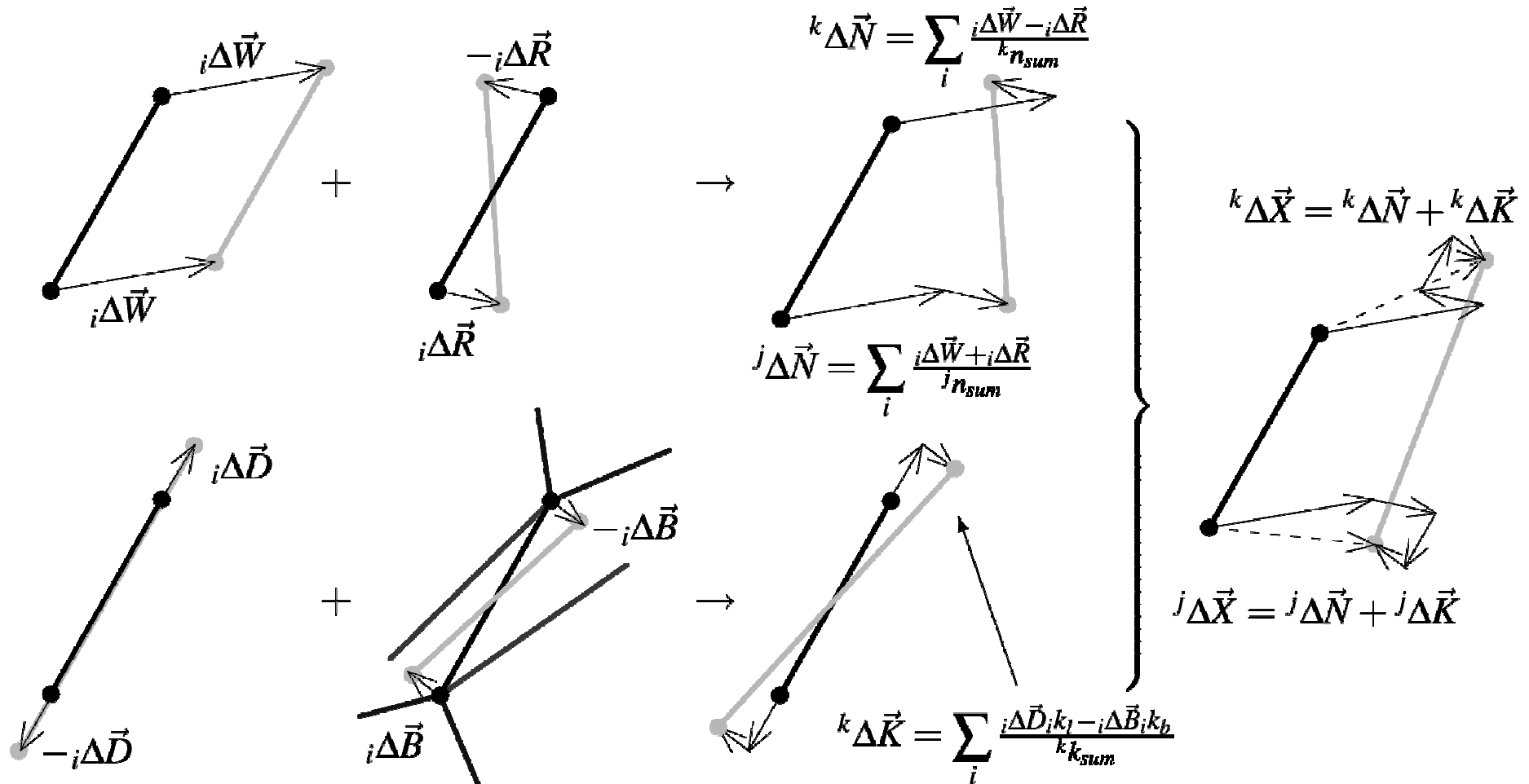
- Own model – the idea of truss lattice was enhanced by angular stiffnesses that control the rigidity of nodes (bending, shearing and torsion).
- It is an approach between a truss (nodes not fixed) and a frame (fixed nodes). The rods that connect nodes do not bend, they are connected by angular springs instead.



Connection of rods at the node

- Elements are removed when critical tensile ϵ_{min} strain is exceeded

Displacement and rotation (2D)



- ΔW – movement, ΔR – rotation,
- ΔD – change of length due to longitudinal stiffness (k_l),
- ΔB – rotation due to bending stiffness (k_b)

Calculating node displacement

$${}^j\Delta\vec{X} = \sum_i \frac{{}_i\Delta\vec{W} + {}_i\Delta\vec{R}}{{}^jn_{sum}} + \frac{\sum_i \frac{1}{{}_id_{init}} ({}_i\Delta\vec{D}_i k_l + {}_i\Delta\vec{B}_i k_b + {}_i\Delta\vec{T}_i k_t)}{\sum_i \frac{1}{{}_id_{init}} ({}_ik_l + {}_ik_b + {}_ik_t)}$$

summation over rod index 'i'

${}_id_{init}$ – initial length of rod 'i'

${}^jn_{sum}$ – total number of rods connected with the node 'j'

ΔW – movement,

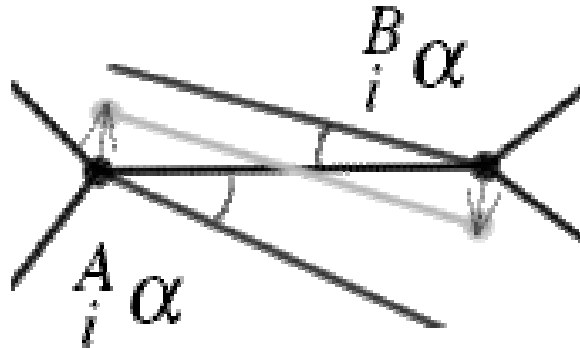
ΔR – rotation,

ΔT – torsional rotation due to torsional stiffness (k_t),

ΔD – change of length due to longitudinal stiffness (k_l),

ΔB – rotation due to bending stiffness (k_b)

Calculation of strain, stress and force



Strain \rightarrow Stress

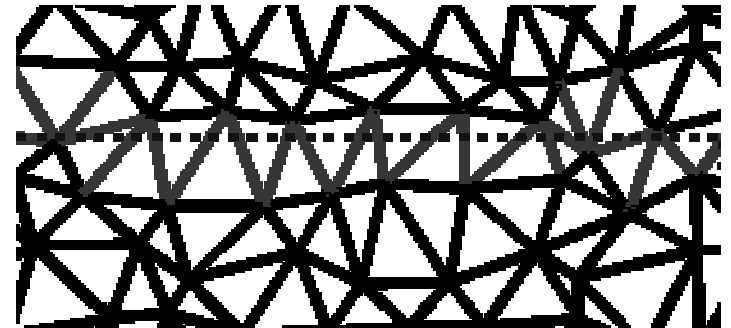
$${}_i \varepsilon = \frac{{}_i d - {}_i d_{init}}{{}_i d_{init}} \quad {}_i \sigma = {}_i \varepsilon E {}_i k_l$$

Shear angle \rightarrow Shear stress

$${}_i \gamma = \frac{{}_i A \alpha + {}_i B \alpha}{2} \quad {}_i \tau = {}_i \gamma G {}_i k_b$$

Bending angle \rightarrow Cosserat bending stress

$${}_i \chi = \frac{{}_i A \alpha - {}_i B \alpha}{2} \quad {}_i m = {}_i \chi G {}_i d^2 {}_i k_b$$



Calculation of section force (ε and γ are projected on normal direction of cross-section plane A)

$$F = A \sum (\varepsilon k_l E + \gamma k_b G)$$

E – Young's modulus

G – Shear modulus

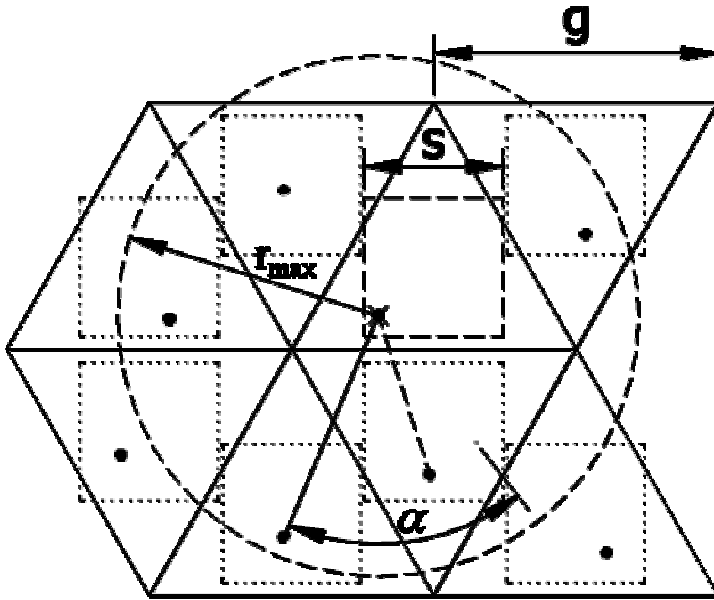
${}_i d$ – element length

${}_i k_l$ – longitudinal stiffness

${}_i k_b$ – bending stiffness

${}_i$ – element index

Mesh generation method



Mesh generation parameters:

g - cell size [m]

r_{\max} - max beam length [m]

α - min angle between beams [rad]

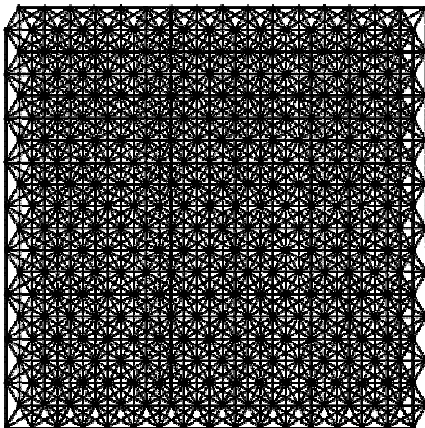
s - mesh irregularity [m]

a) $s = 0$

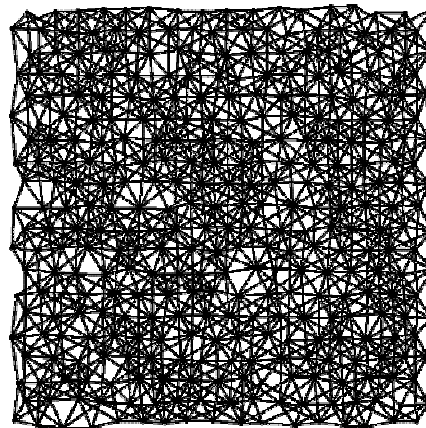
b) $s = 0.3$

c) $s = 0.6$

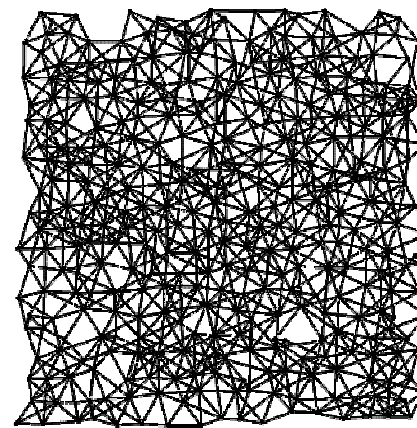
d) $s = 0.6$, Delaunay



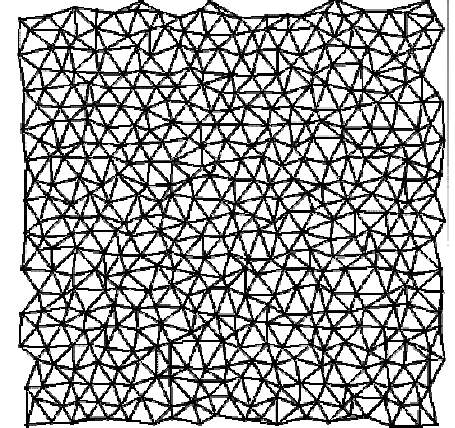
a)



b)



c)



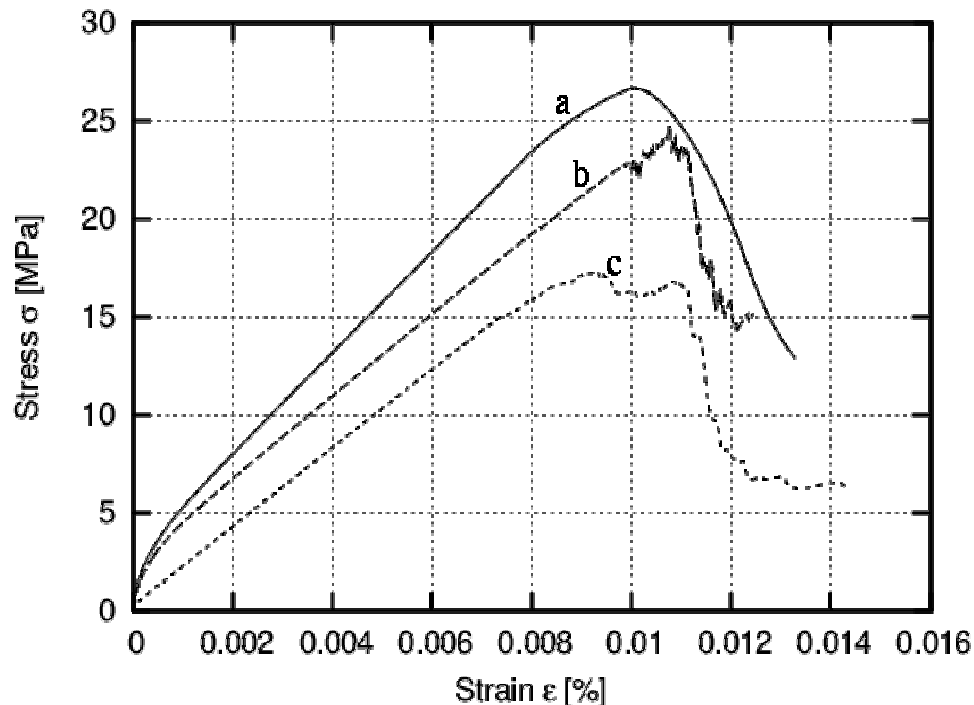
d)

Parameters used to describe the model

Group 1	Stiffness parameters
	k_l longitudinal stiffness [-]
	k_b bending stiffness [-]
	k_t torsional stiffness [-]
Group 2	Fracture parameters
	ϵ_{min} critical tensile strain [-]
Group 3	Mesh generation parameters
	g cell size [m]
	r_{max} max beam length [m]*
	α min angle between beams [rad]*
	s mesh irregularity [m]

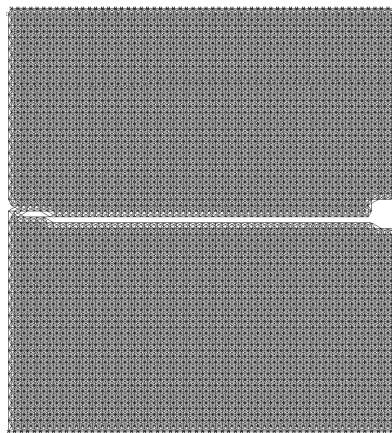
* *parameters used only with non-Delaunay generation method*

Effect of mesh irregularity

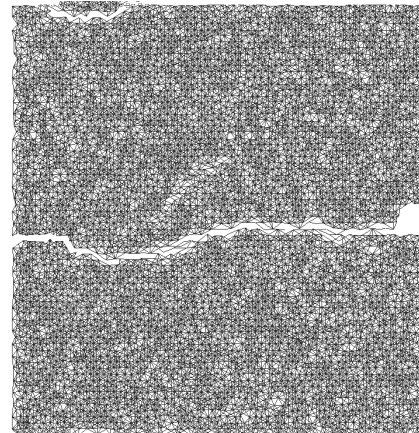


Effect of mesh irregularity parameter 's' on the stress-strain curve and crack pattern.

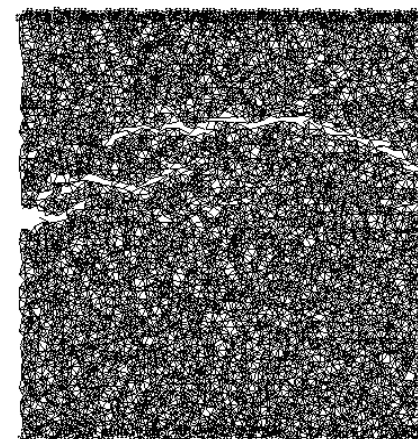
$\alpha=20^\circ$, $r_{max}=2g$, $k_b/k_l=0.6$
elements removed when $\epsilon_{min}=0.02\%$



a)



b)



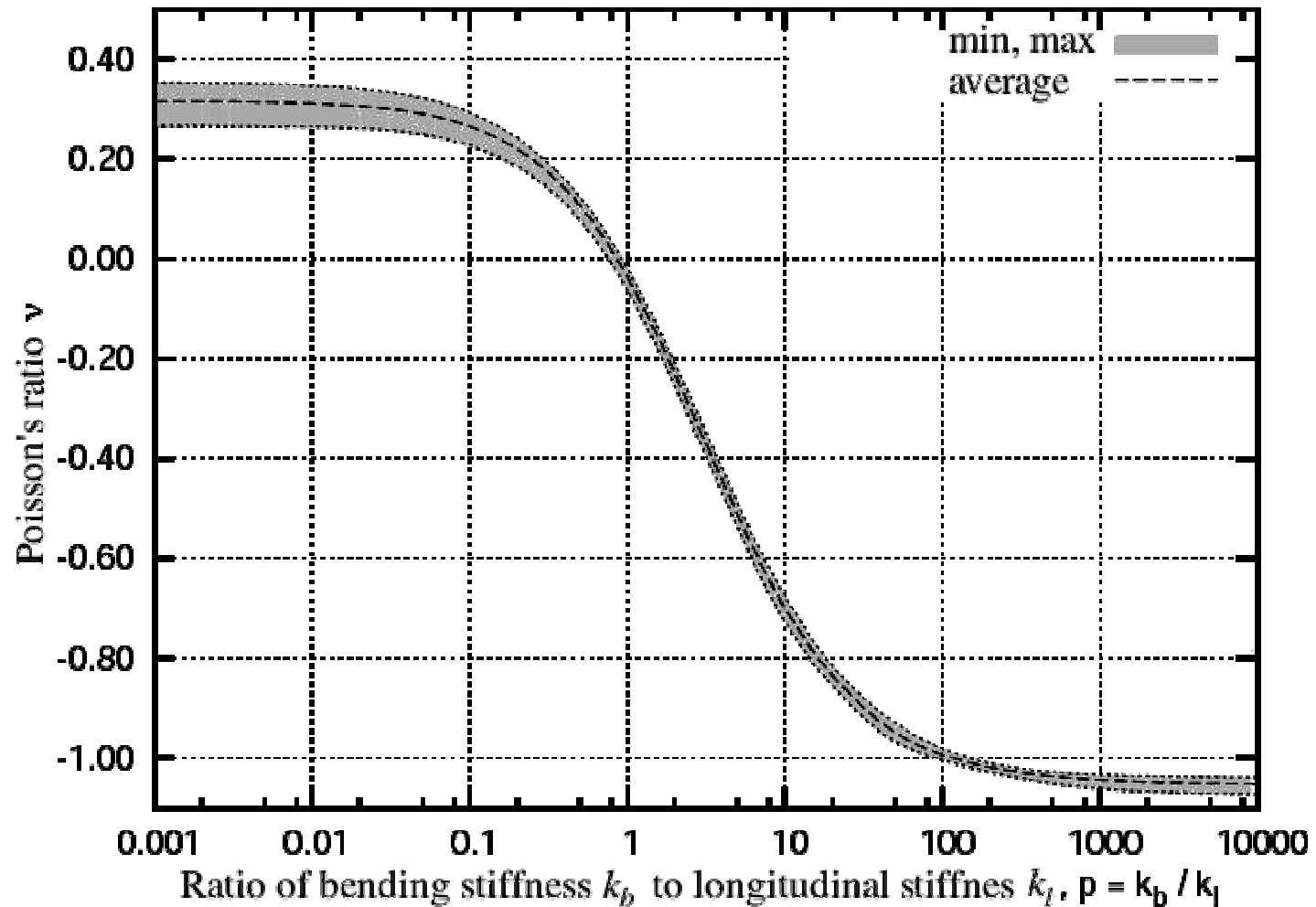
c)

a) $s = 0$

b) $s = 0.3$

c) $s = 0.6$

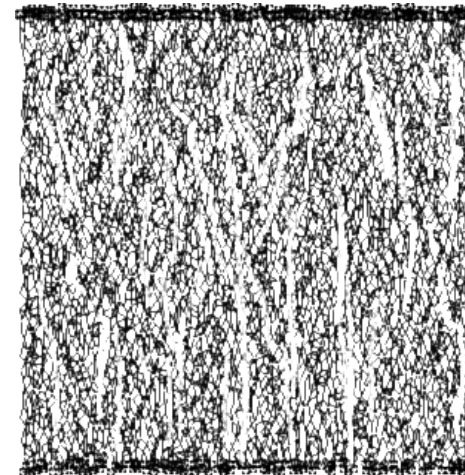
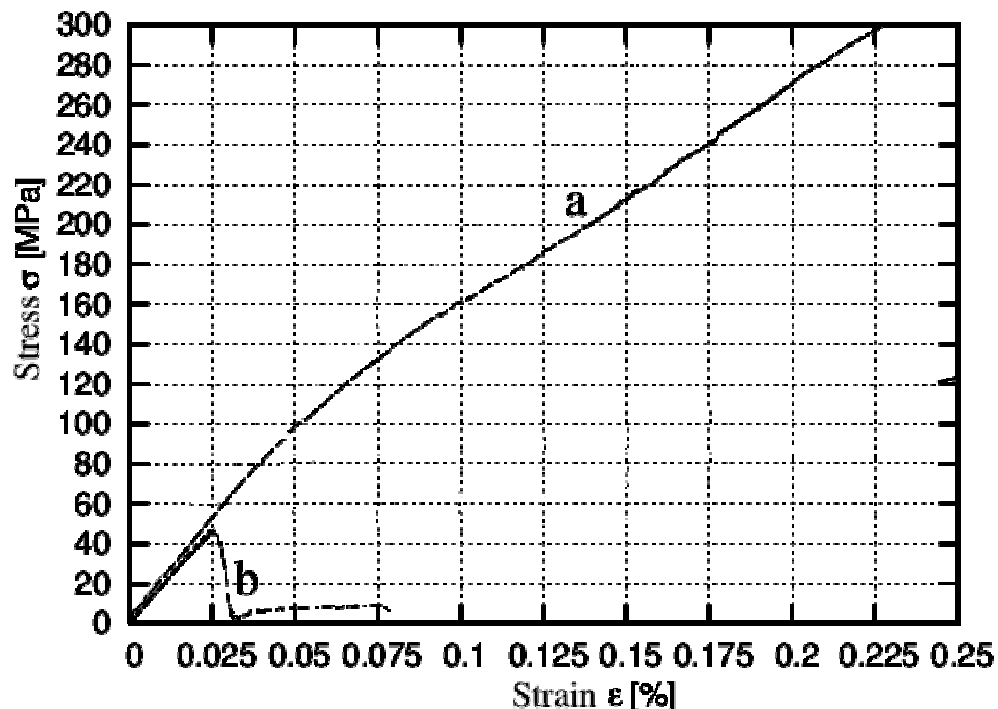
Influence of k_b on Poisson's ratio



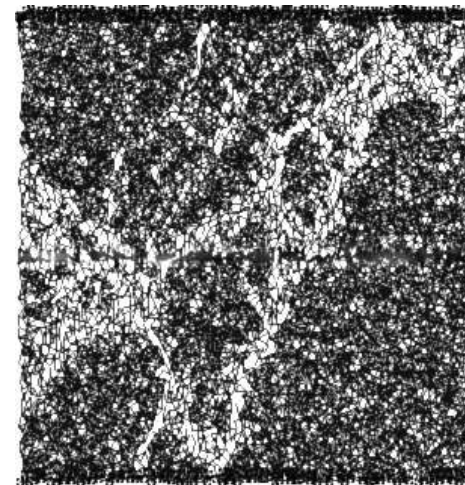
Ratio between bending and longitudinal stiffness $p = k_b / k_l$ determines the Poisson's ratio of the lattice mesh

Uniaxial compression (single phase)

Effect of stiffness ratio $p=k_b/k_l$ on stress-strain curve in uniaxial compression with smooth edges (elements removed when $\varepsilon_{min}=0.02\%$)



a) $p=0.3$



b) $p=0.001$

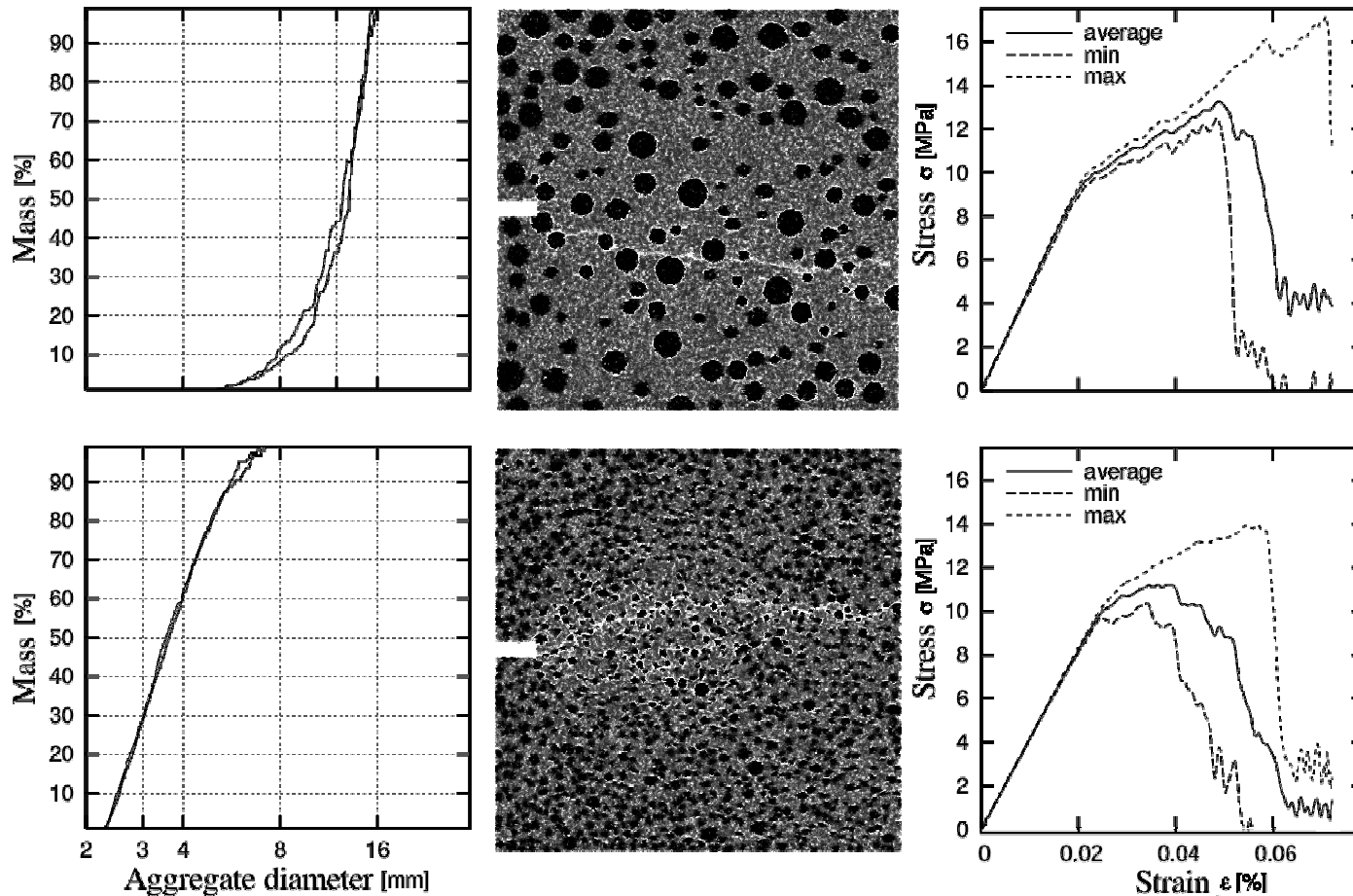
Effect of p on fracture pattern

Effect of aggregates – three phases 2D (25%)

Interfacial zone: $k_l=0.7, k_b=0.5, \epsilon_{min}=0.005\%$,

Cement matrix: $k_l=1.0, k_b=0.7, \epsilon_{min}=0.02\%$

Aggregate: $k_l=3.0, k_b=2.1, \epsilon_{min}=0.0133\%$



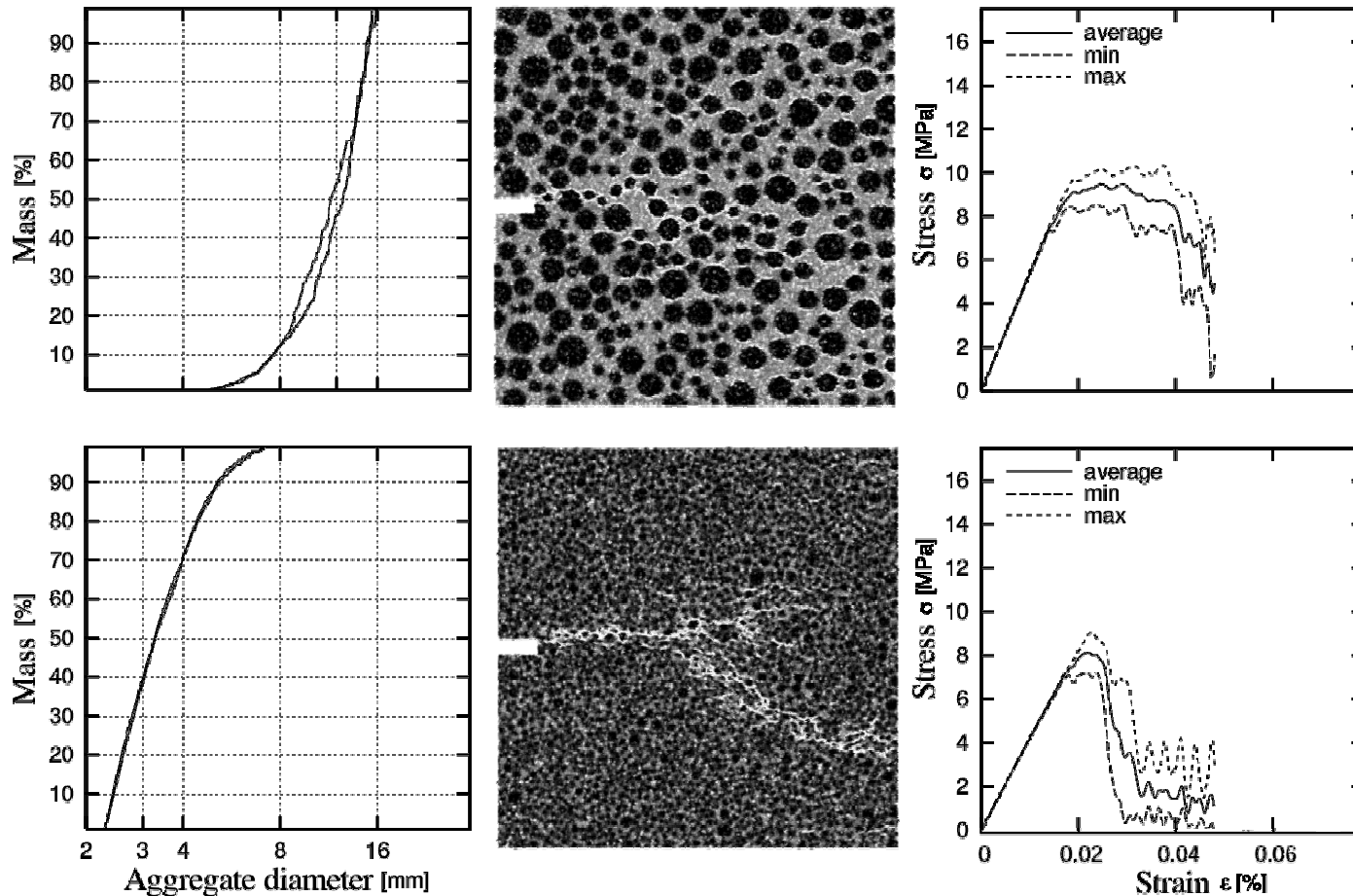
Uniaxial extension – 2 different sieve curves

Effect of aggregates – three phases 2D (50%)

Interfacial zone: $k_l=0.7$, $k_b=0.5$, $\epsilon_{min}=0.005\%$,

Cement matrix: $k_l=1.0$, $k_b=0.7$, $\epsilon_{min}=0.02\%$

Aggregate: $k_l=3.0$, $k_b=2.1$, $\epsilon_{min}=0.0133\%$



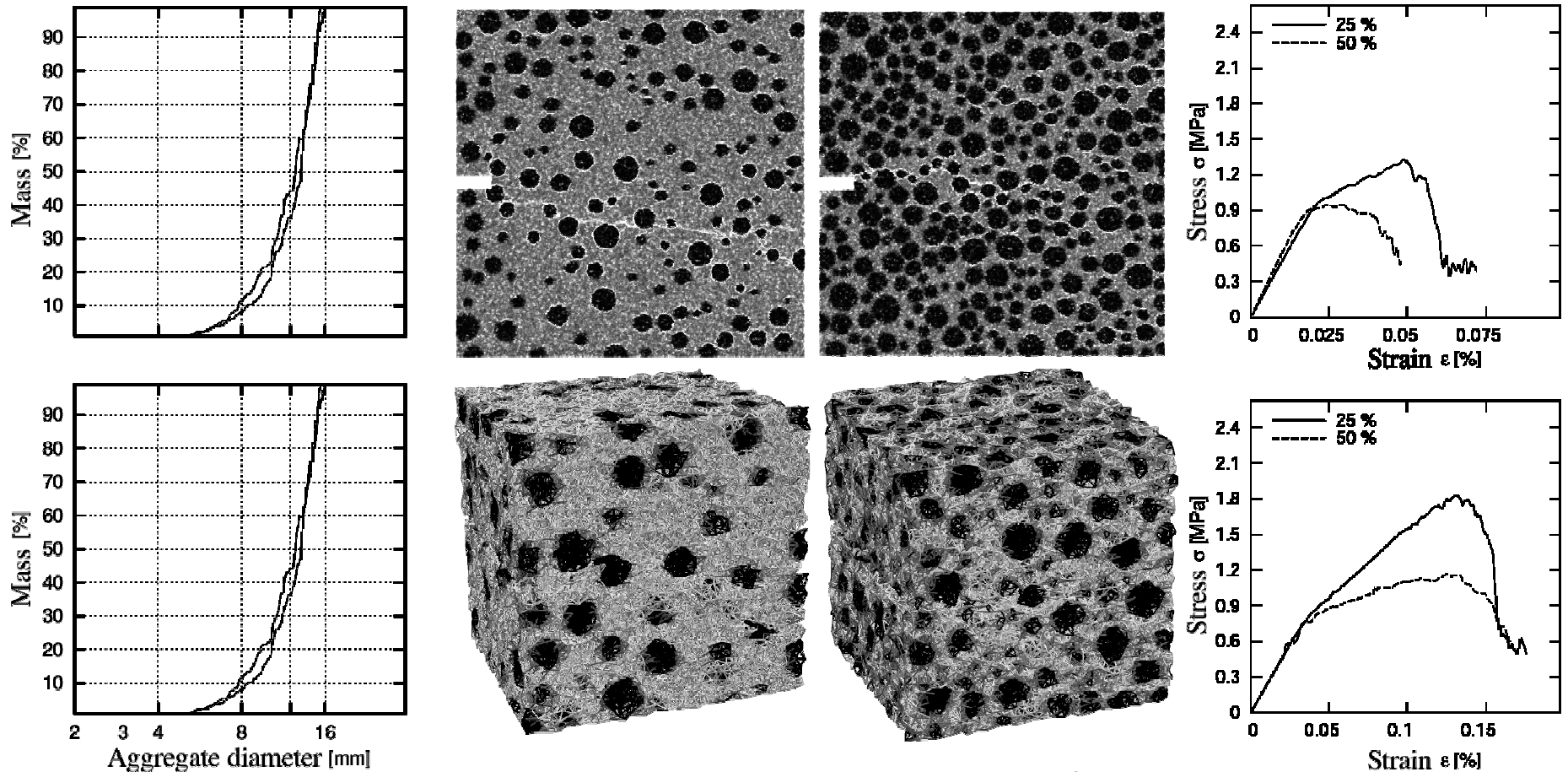
Uniaxial extension – 2 different sieve curves

Effect of aggregates – three phases 2D / 3D (25% / 50%)

Interfacial zone: $k_l=0.7$, $k_b=0.5$, $\epsilon_{min}=0.005\%$,

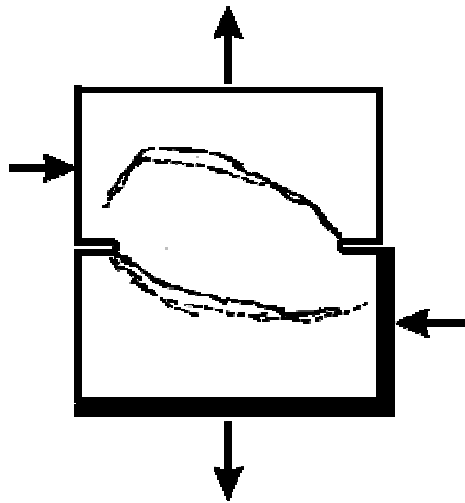
Cement matrix: $k_l=1.0$, $k_b=0.7$, $\epsilon_{min}=0.02\%$

Aggregate: $k_l=3.0$, $k_b=2.1$, $\epsilon_{min}=0.0133\%$

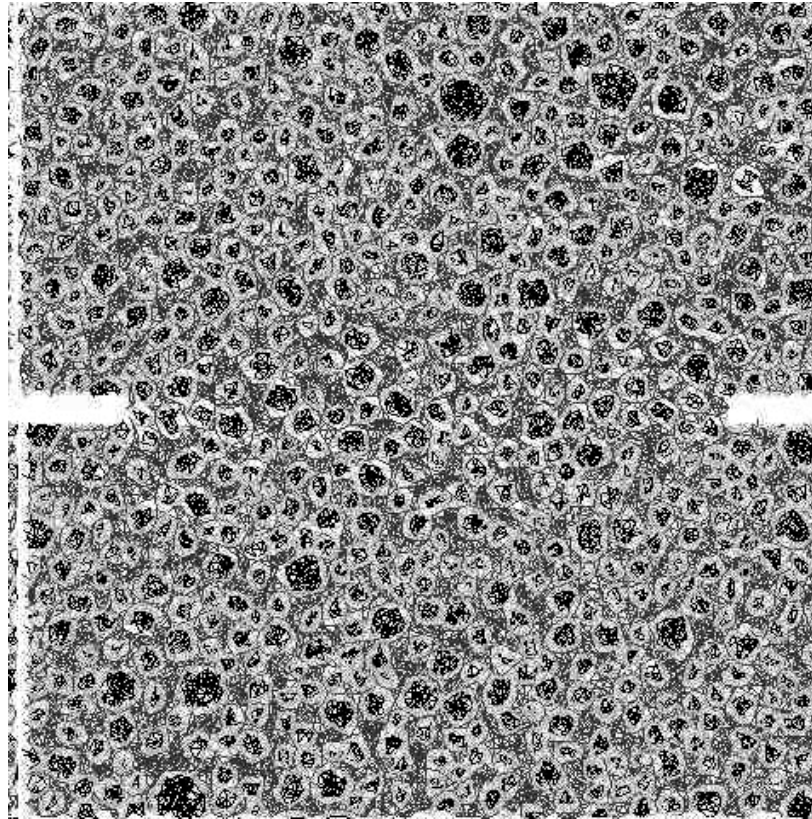


Uniaxial extension – 25% and 50% of aggregate volume/area

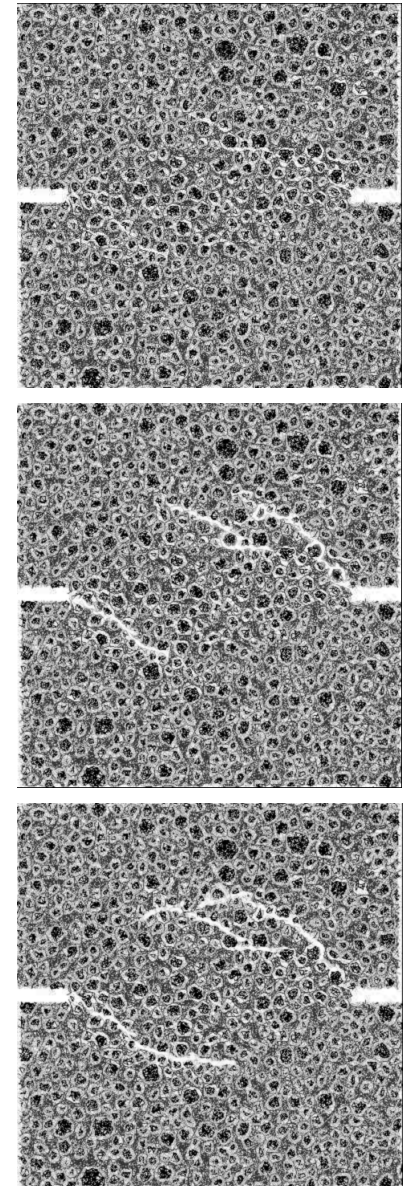
Nooru-Mohamed test (propagation of curved crack) three phase material, 2D



Experimental
fracture pattern
(Nooru-Mohamed 1992)



Crack propagation in numerical results

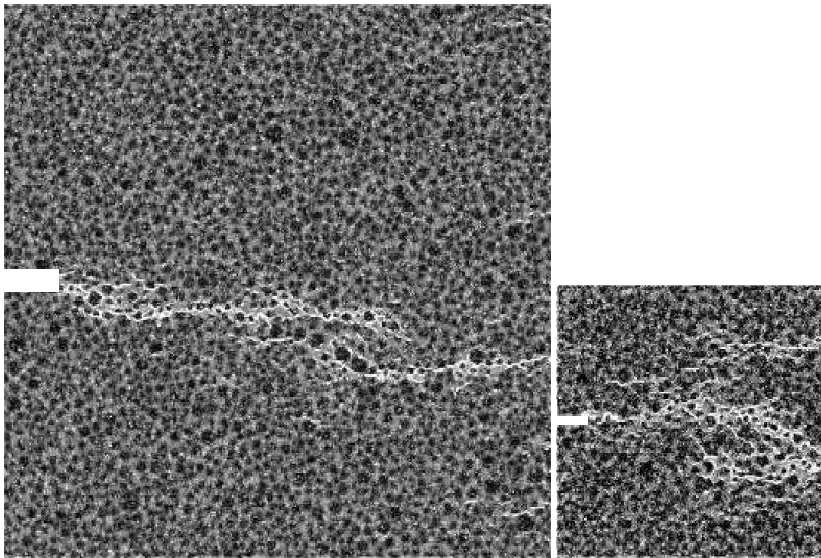


Size effect in numerical results (three phases 2D)

Interfacial zone: $k_l=0.7, k_b=0.5, \varepsilon_{min}=0.005\%$,

Cement matrix: $k_l=1.0, k_b=0.7, \varepsilon_{min}=0.02\%$

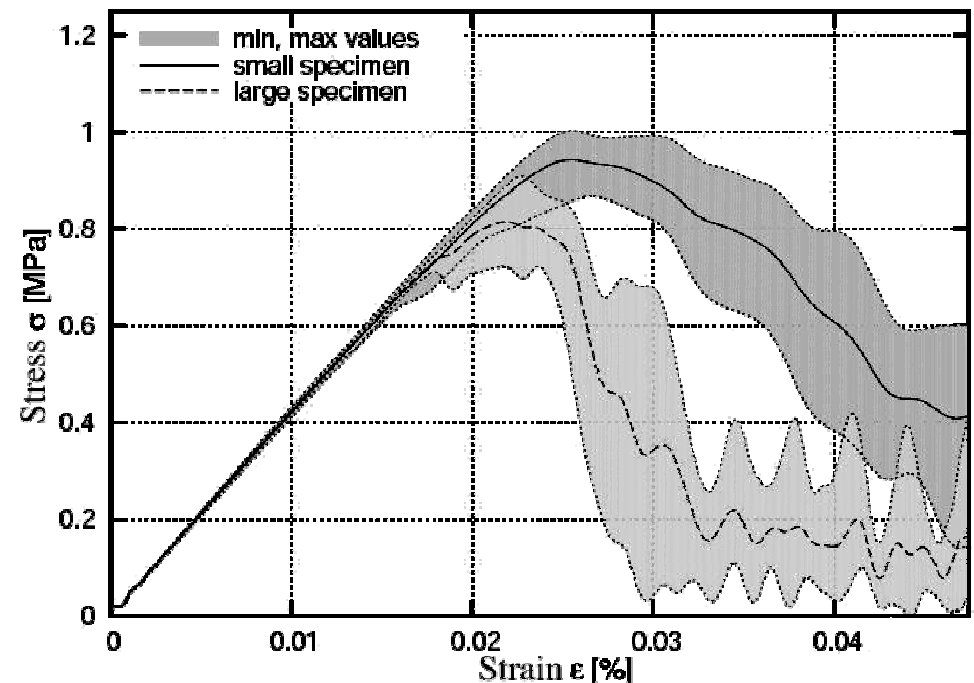
Aggregate: $k_l=3.0, k_b=2.1, \varepsilon_{min}=0.0133\%$



Fracture propagation:

small specimen: $10 \times 10 \text{ cm}^2$

large specimen: $20 \times 20 \text{ cm}^2$



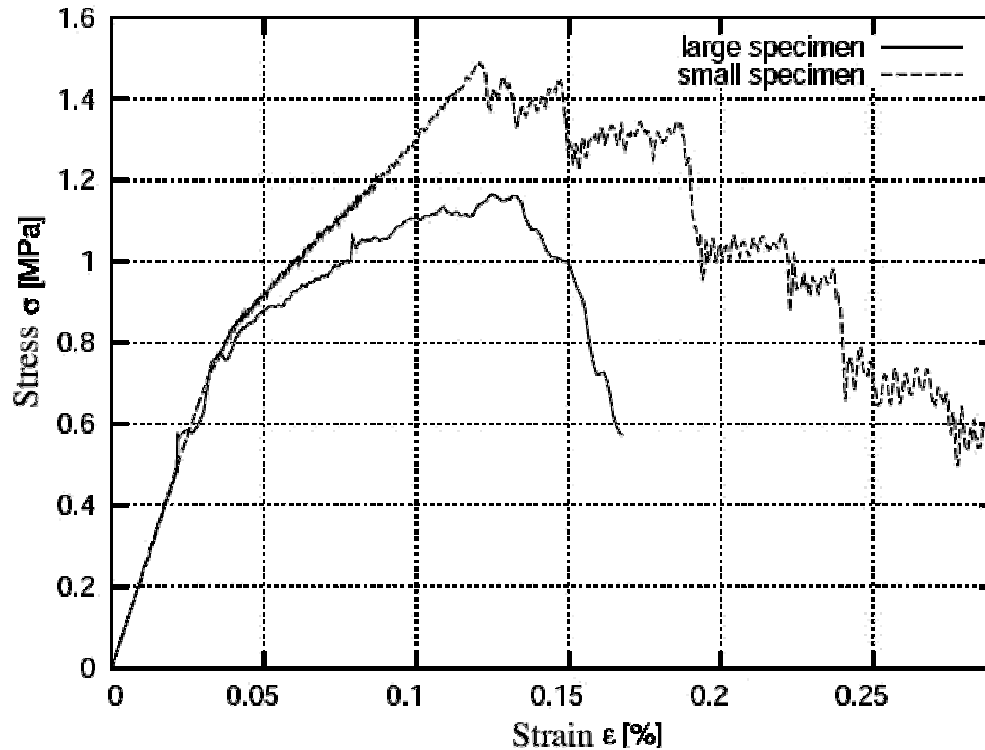
Stress-strain curve for **2D** specimens with different sizes subject to uniaxial extension with smooth edges

Size effect in numerical results (three phases 3D)

Interfacial zone: $k_t=0.7, k_b=0.5, \epsilon_{min}=0.005\%$,

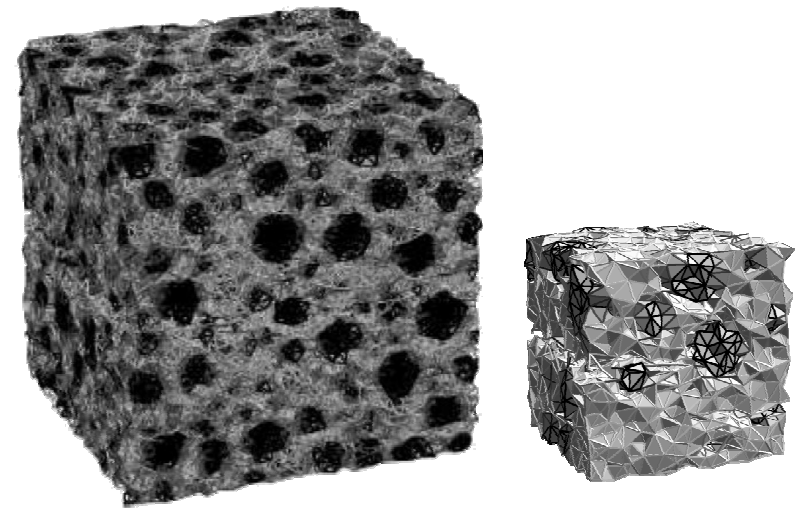
Cement matrix: $k_t=1.0, k_b=0.7, \epsilon_{min}=0.02\%$

Aggregate: $k_t=3.0, k_b=2.1, \epsilon_{min}=0.0133\%$



Stress-strain curve for **3D** specimens with different sizes subject to uniaxial extension with smooth edges

Assuming $k_t=k_b$



large specimen: $10 \times 10 \times 10 \text{ cm}^3$

small specimen: $5 \times 5 \times 5 \text{ cm}^3$

Conclusions

- Lattice model allows to study fracture propagation on the scale of cement matrix and aggregates.
- The peak-load decreases with increasing particle density.
- Ductility increases with increasing aggregate size and density.
- Small particle density leads to non-linearity in the pre-peak regime. High particle density leads to straight pre-peak stress-strain behaviour.